

6.5 Laplace transform and system functions

Name: _____ Class: _____ Date: _____

Total: 23 marks**KEY WORDS** system function • poles and zeros • frequency response

Objective

Move between $h(t)$, $H(s)$ and $H(j\omega)$; read natural modes from poles; assess stability from the pole locations; and verify time- and frequency-domain answers against each other.

1 Key knowledge and worked examples

■ The system function

$H(s) = Y(s)/X(s)$, and $h(t) \leftrightarrow H(s)$. For rational $H(s) = \text{poles/zeros} + \text{constant}$: each real pole p contributes a mode e^{pt} to the impulse response; complex poles contribute decaying sinusoids at the pole angle. The ROC must include the $j\omega$ axis for a stable system – equivalently, all poles in the open left half-plane.

■ Worked example: one pole, three views

$H(s) = 1/(s+1)$:

- $h(t) = e^{-t}u(t)$ (pole at -1 is the exponent).
- Step response $1/(s(s+1)) = 1/s - 1/(s+1) \rightarrow 1 - e^{-t}$ – the unit 6.2 result, now by algebra.
- **Frequency response** $H(j\omega) = 1/(1 + j\omega)$: gain $1/\sqrt{2}$ at $\omega = 1$ (the pole magnitude), phase -45° there, -90° at ∞ .

One pole, three consistent views – the checks write themselves.

■ Composition in the s-domain

Cascade: $H = H_1 \cdot H_2$ (poles and zeros combine). Feedback $H = G/(1 + GH)$ – the denominator's roots are the closed-loop poles, and their left-half-plane membership is the stability verdict (the subject EE10 takes to design).

2 Practice

2.1 $H(s) = 10/(s+5)$: give $h(t)$, the DC gain, and the -3 dB frequency. [3]

2.2 A system has poles at $s = -2$ and $s = -1 \pm j10$. Write the form of its natural response (no coefficients). [3]

2.3 $H(s) = 1/((s+1)(s-2))$: is the causal system stable? Why (one sentence)? [2]

3 Exam-style questions

3.1 An LTI system: $H(s) = s/(s^2 + 2s + 101)$.

Factor the poles, write the general impulse response (with unknown coefficients), and solve them from $h(0^+) = 0$ and the initial slope $h'(0^+) = 1$ (the transform's high-frequency behaviour). Then compute $|H(j\omega)|$ at $\omega = 10$ and at $\omega = 0$, and state the type of filter this is. [8]

3.2 A unity-feedback system: open loop $G(s) = K/((s + 1)(s + 2))$.

Compute the closed-loop $H(s)$, the poles as a function of K , and the stability condition on K (Routh or direct root inspection). Then evaluate the pole locations at $K = 2$ and verify the DC closed-loop gain is $H(0) = 2/(2+2) = 1/2$. [7]
