6.2 Datapath and control

Name: _____ Class: _____ Date: _____ **Total: 24 marks**

KEY WORDS datapath • control

Objective

Walk the single-cycle datapath, set its control bits, and compute the cycle time.

1 Key knowledge and worked examples

■ The six bits

`lw R4, 8(R1)`: RegWrite 1, MemRead 1, MemToReg 1, ALUSrc 1, Branch 0, MemWrite 0 ✓. `sw` flips the port: RegWrite 0, MemWrite 1, MemToReg becomes a don't-care ✓.

■ Worked example: the slowest citizen

IM 200 + RF 100 + ALU 200 + DM 250 + wiring 150 = 900 ps for `lw`; the single cycle is 900 ps and 100 instructions take 90 000 ps ✓.

2 Practice

2.1 Name the five blocks an `lw` passes through, in order. [3]

2.2 For `sw R5, 12(R1)`, give RegWrite, MemWrite and MemRead. [3]

2.3 State what a don't-care control bit means. [3]

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3 Exam-style questions

3.1 Parameters: IM 200 ps, RF read 100 ps, ALU 200 ps, DM 250 ps, RF write 100 ps, wiring 150 ps total.

Compute the `lw` path time and state the clock cycle. Compute the `add` path (IM + RF + ALU + wiring, no DM) and explain why it does not set the cycle. Compute the total time for 100 instructions (mixed), and the new cycle time if DM improves to 150 ps, with the new total. [8]

3.2 For each instruction, give all six control bits and one line of justification: `lw R2, 0(R1)`; `sw R3, 4(R1)`; `beq R1, R0, next`; `add R4, R1, R2`.

State which bits a `beq` sets differently from the handout's `lw` row and what the datapath does when the branch is not taken. [7]

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