

3. A triangular rod, shown above, has length L , mass M , and a nonuniform linear mass density given by the equation $\lambda = \frac{2M}{L^2}x$, where x is the distance from one end of the rod.

(a) Using integral calculus, show that the rotational inertia of the rod about its left end is $ML^2/2$.

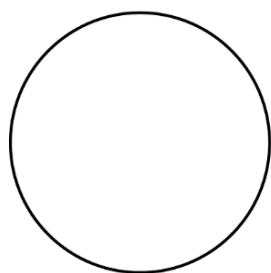


Figure 1

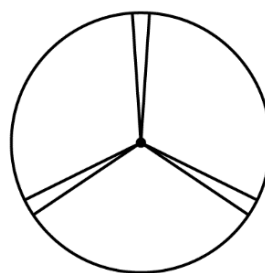


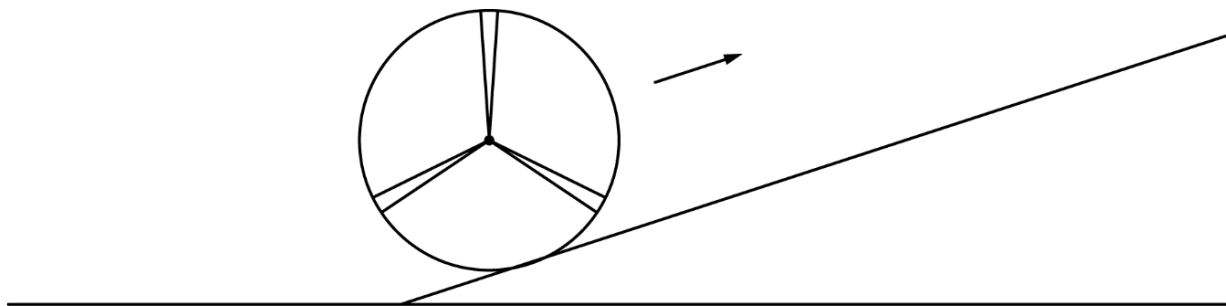
Figure 2

The thin hoop shown above in Figure 1 has a mass M , radius L , and a rotational inertia around its center of ML^2 . Three rods identical to the rod from part (a) are now fastened to the thin hoop, as shown in Figure 2 above.

- (b) Derive an expression for the rotational inertia I_{tot} of the hoop-rods system about the center of the hoop. Express your answer in terms of M , L , and physical constants, as appropriate.

The hoop-rods system is initially at rest and held in place but is free to rotate around its center. A constant force F is exerted tangent to the hoop for a time Δt .

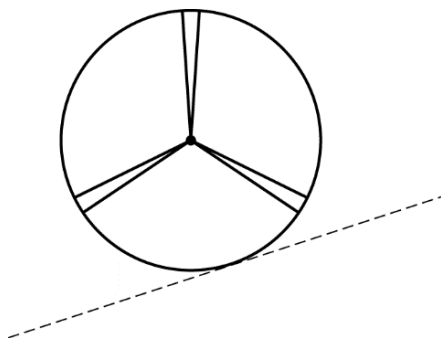
- (c) Derive an expression for the final angular speed ω of the hoop-rods system. Express your answer in terms of M , L , F , Δt , and physical constants, as appropriate.



The hoop-rods system is rolling without slipping along a level horizontal surface with the angular speed ω found in part (c). At time $t = 0$, the system begins rolling without slipping up a ramp, as shown in the figure above.

(d)

- i. On the figure of the hoop-rods system below, draw and label the forces (not components) that act on the system. Each force must be represented by a distinct arrow starting at, and pointing away from, the point at which the force is exerted on the system.



- ii. Justify your choice for the direction of each of the forces drawn in part (d)i.

- (e) Derive an expression for the change in height of the center of the hoop from the moment it reaches the bottom of the ramp until the moment it reaches its maximum height. Express your answer in terms of M , L , I_{tot} , ω , and physical constants, as appropriate.

STOP

END OF EXAM