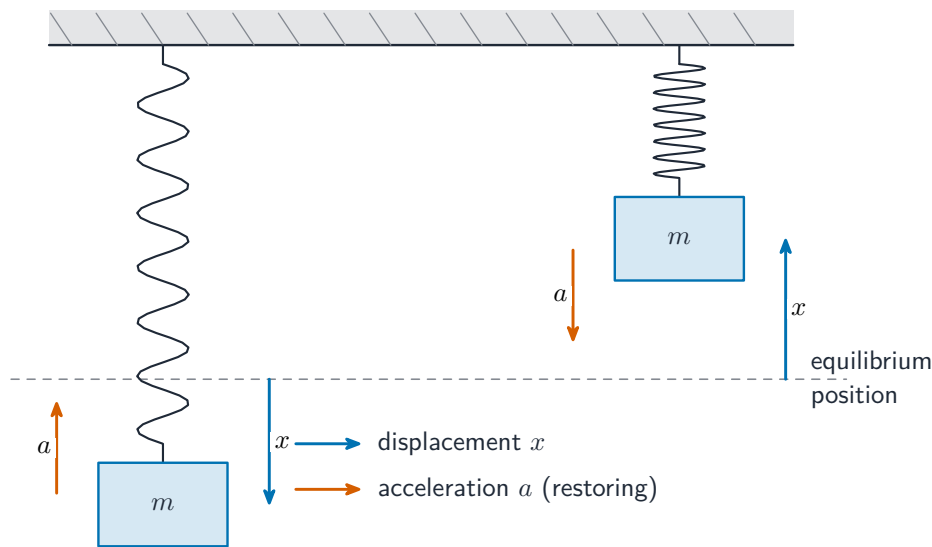


# Oscillations

## AP Physics 1

### Defining Simple Harmonic Motion

**Simple harmonic motion** 简谐运动 (SHM) is a back-and-forth **oscillation** 振动 caused by a **restoring force** 回复力 that is proportional to the displacement from equilibrium and always points back toward it:  $F = -kx$ . A mass on a spring and (for small angles) a pendulum are the standard examples. Because the force grows with displacement, the motion is smooth and repeating, tracing a sine curve in time.



*In SHM the acceleration always points back towards equilibrium, opposite the displacement*

The test for SHM is exactly this: acceleration proportional to displacement and opposite in direction,  $a = -\frac{k}{m}x$ . A pendulum only obeys it for **small** swings, where  $\sin \theta \approx \theta$ ; large swings are not quite SHM.

### Frequency and Period of SHM

- The **period** 周期  $T$  is the time for one full cycle.
- The **frequency** 频率  $f = \frac{1}{T}$  is cycles per second (hertz).

For SHM these depend only on the system, **not** on the amplitude:

$$T_{\text{spring}} = 2\pi\sqrt{\frac{m}{k}}, \quad T_{\text{pendulum}} = 2\pi\sqrt{\frac{L}{g}}$$

So a stiffer spring or smaller mass oscillates faster; a longer pendulum swings slower.

**Worked example.** A 0.25 kg mass hangs on a spring of stiffness  $k = 100 \text{ N/m}$ . Its period is

$$T = 2\pi\sqrt{\frac{m}{k}} = 2\pi\sqrt{\frac{0.25}{100}} = 0.31 \text{ s}, \quad f = \frac{1}{T} = 3.2 \text{ Hz}.$$

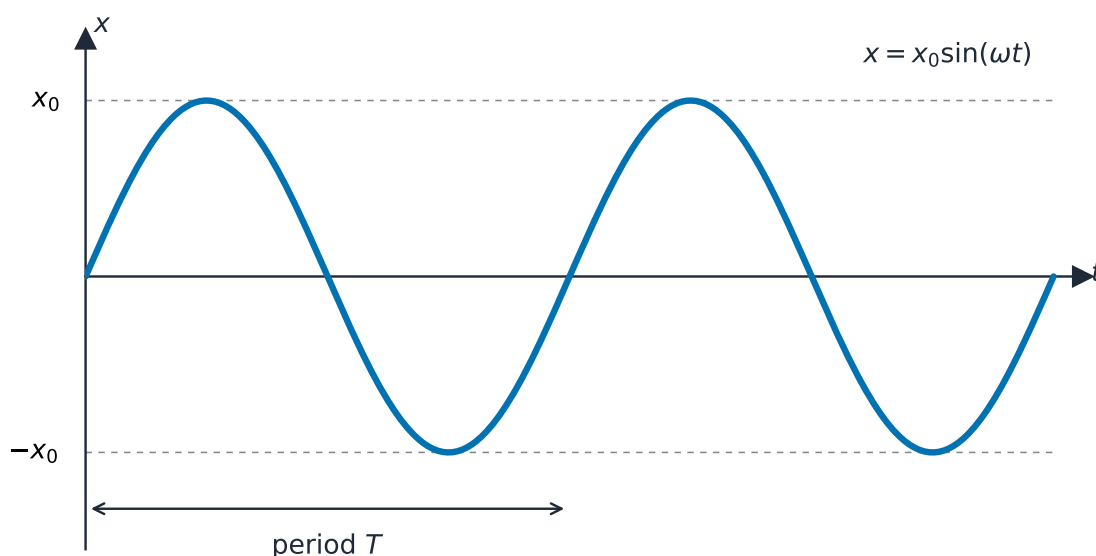
**Worked example.** A pendulum clock ticks with a period of exactly 2.0 s. How long is it? Rearranging  $T = 2\pi\sqrt{L/g}$ ,

$$L = g\left(\frac{T}{2\pi}\right)^2 = 9.8 \times \left(\frac{2.0}{2\pi}\right)^2 = 0.99 \text{ m}.$$

Notice the amplitude never entered –a wide or narrow swing keeps the same time, which is what makes pendulums good clocks.

## Representing and Analyzing SHM

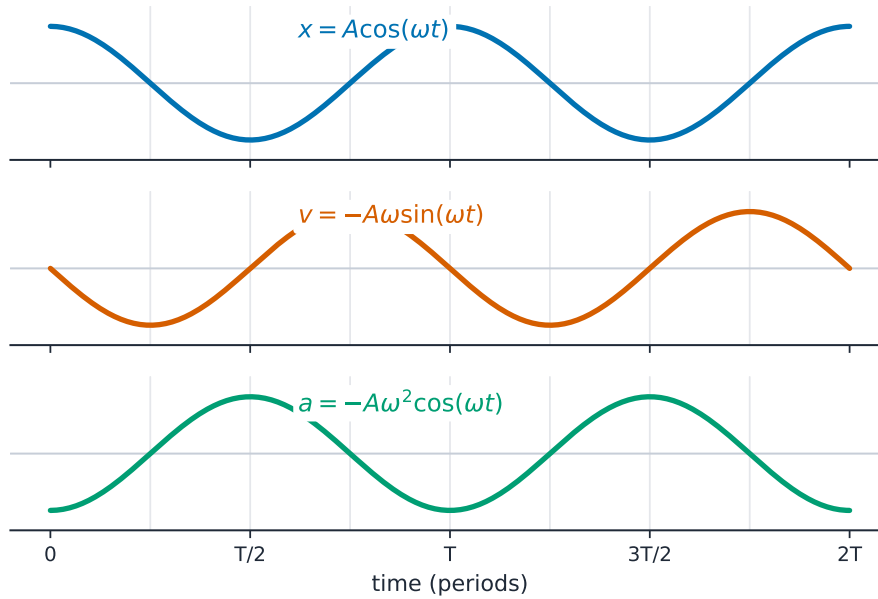
The displacement varies sinusoidally:  $x(t) = A \cos(\omega t)$  (or sine), where  $A$  is the **amplitude** 振幅 (maximum displacement) and  $\omega = 2\pi f$  is the **angular frequency** 角频率. Reading the motion:



*Displacement varies sinusoidally with time in simple harmonic motion*

- At the **extremes** ( $x = \pm A$ ): displacement and restoring force are maximum, so acceleration is maximum, but velocity is **zero**.
- At **equilibrium** 平衡位置 ( $x = 0$ ): force and acceleration are zero, but **speed is maximum**.

Velocity and acceleration are also sinusoidal, shifted in **phase** 相位 from the displacement –velocity leads displacement by a quarter cycle, and acceleration is exactly opposite to displacement.



*Displacement, velocity, and acceleration in SHM, each a quarter-cycle apart*

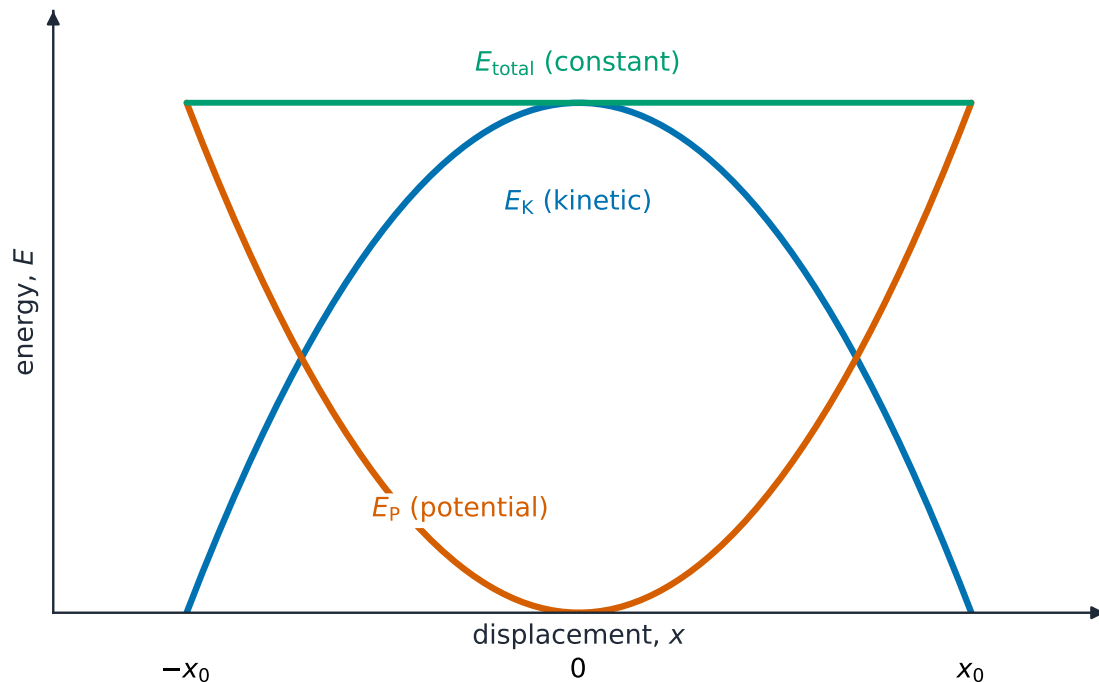
Read the figure as a story: where  $x$  is largest (the turning point),  $v$  has just fallen to zero and  $a$  is at its most negative, hauling the mass back; a quarter-cycle later the mass races through the middle at top speed with zero acceleration.

## Energy of Simple Harmonic Oscillators

Energy sloshes between kinetic and potential while the **total** stays constant (no friction):

$$E = \frac{1}{2}kA^2 = \frac{1}{2}kx^2 + \frac{1}{2}mv^2.$$

At the extremes it is **all potential**; at equilibrium it is **all kinetic** (maximum speed). Because  $E \propto A^2$ , doubling the amplitude quadruples the energy.



*Kinetic and potential energy swap over a cycle while the total energy stays constant*

**Worked example.** A 0.50 kg mass on a spring of stiffness  $k = 200$  N/m oscillates with amplitude  $A = 0.10$  m. Find its maximum speed. All the energy is kinetic at the equilibrium point, so  $\frac{1}{2}kA^2 = \frac{1}{2}mv_{\max}^2$ :

$$v_{\max} = A\sqrt{\frac{k}{m}} = 0.10 \times \sqrt{\frac{200}{0.50}} = 0.10 \times 20 = 2.0 \text{ m/s.}$$

The energy method is faster than tracking the sine functions when you only need the greatest speed.

## Exam tips

- Test for **SHM**: the acceleration must be proportional to the displacement and directed back toward the middle ( $a = -\frac{k}{m}x$ ).
- The **period does not depend on amplitude** —use  $T = 2\pi\sqrt{m/k}$  (spring) or  $T = 2\pi\sqrt{L/g}$  (pendulum, small angles).
- Speed is **maximum at the middle** (all kinetic) and **zero at the extremes** (all potential); acceleration is largest at the extremes.
- Use energy ( $\frac{1}{2}kA^2 = \frac{1}{2}kx^2 + \frac{1}{2}mv^2$ ) to find the maximum speed quickly:  $v_{\max} = A\sqrt{k/m}$ .
- Total energy  $\propto A^2$ , so doubling the amplitude quadruples the energy.