

MF19 carries a Further Mathematics section: the summation formulae, the Maclaurin series, the hyperbolic identities and the standard statistical tests. It does not carry the matrix methods, the vector geometry results or the differential-equation techniques that most of the paper actually consists of.

Given in MF19 – further sections

- The summations $\sum r$, $\sum r^2$ and $\sum r^3$ in closed form.
- Maclaurin expansions, including those for $\sinh x$, $\cosh x$, $\arctan x$ and $\arcsin x$.
- The hyperbolic identities and the logarithmic forms of the inverse hyperbolic functions.
- Statistics: the t , χ^2 and F distributions with their tables, and the standard formulae for the correlation coefficient and the regression line.
- Mechanics: moments of inertia of standard bodies, and the formulae for elastic strings and simple harmonic motion.

You must know – matrices and linear algebra

- Determinant and inverse** – For a 2×2 matrix, $\det = ad - bc$ and the inverse is $\frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$. A zero determinant means singular: no inverse, and the transformation collapses the plane onto a line.
- What the determinant means** – Its absolute value is the area (or volume) scale factor of the transformation, and a negative value means orientation is reversed.
- Eigenvalues and eigenvectors** – Solve $\det(\mathbf{A} - \lambda \mathbf{I}) = 0$ for λ , then $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$ for each eigenvector. Diagonalisation gives $\mathbf{A} = \mathbf{PDP}^{-1}$, and hence $\mathbf{A}^n = \mathbf{PD}^n\mathbf{P}^{-1}$.
- Systems of equations** – Row-reduce the augmented matrix. A row of zeros equalling a non-zero constant means inconsistent; a row entirely of zeros means infinitely many solutions, which must then be given in parametric form.

You must know – complex numbers and roots

- Modulus-argument form** – $z = r(\cos \theta + i \sin \theta) = re^{i\theta}$; multiplying multiplies moduli and adds arguments.
- De Moivre** – $(re^{i\theta})^n = r^ne^{in\theta}$, which gives both the multiple-angle identities and the n th roots, spaced $2\pi/n$ apart around a circle.
- Roots of polynomials** – For $ax^3 + bx^2 + cx + d = 0$: $\sum \alpha = -b/a$, $\sum \alpha\beta = c/a$, $\alpha\beta\gamma = -d/a$. New equations with transformed roots come from a substitution, not from solving.
- Loci in the complex plane** – $|z - a| = r$ is a circle; $|z - a| = |z - b|$ is the perpendicular bisector; $\arg(z - a) = \theta$ is a half-line from a , excluding a itself.

You must know – calculus and differential equations

- First-order linear equations** – Write it as $\frac{dy}{dx} + P(x)y = Q(x)$, multiply by the integrating factor $e^{\int P dx}$, then the left side is the derivative of $y \times$ that factor.
- Second-order equations** – Solve the auxiliary equation; real distinct roots give $Ae^{m_1x} + Be^{m_2x}$, a repeated root gives $(A + Bx)e^{mx}$, complex roots give $e^{px}(A \cos qx + B \sin qx)$. Then add a particular integral matched to the right-hand side.
- Reduction formulae** – Integrate by parts once to express I_n in terms of I_{n-2} , and state the base case. The exam always asks for the base case separately.
- Arc length and surface area** – $s = \int \sqrt{1 + (dy/dx)^2} dx$, and for a surface of revolution about the x -axis, $S = 2\pi \int y \sqrt{1 + (dy/dx)^2} dx$.
- Polar coordinates** – Area = $\frac{1}{2} \int r^2 d\theta$. Getting the limits right – where the curve actually starts and finishes – carries more marks than the integration.

You must know – vector geometry

- Vector product** – $|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}| \sin \theta$, giving the area of a parallelogram; the result is perpendicular to both, so it supplies a plane’s normal.
- Lines and planes** – Line: $\mathbf{r} = \mathbf{a} + t\mathbf{b}$. Plane: $\mathbf{r} \cdot \mathbf{n} = d$. The angle between two planes is the angle between their normals; between a line and a plane it is the complement of that.
- Distances** – Point to plane: $|\mathbf{a} \cdot \hat{\mathbf{n}} - d|$. Between skew lines: project the joining vector onto the common perpendicular $\mathbf{b}_1 \times \mathbf{b}_2$.

Where Further Maths marks are won and lost

- Method marks dominate. State the technique – “using the integrating factor”, “by de Moivre” – before the algebra, because a stated method survives an arithmetic slip.
- Proof by induction has a fixed shape and is marked against it: verify the base case, assume for $n = k$, prove for $n = k + 1$, then write the concluding sentence. The conclusion is a mark of its own and is the one most often missing.
- Give exact answers throughout unless a decimal is asked for, and check a complex-number argument lies in the required range before writing it down.