

18.1 Artificial Intelligence (AI)

Name: _____ Class: _____ Date: _____

Total: 32 marks

KEY WORDS artificial intelligence 人工智能 • deep learning 深度学习

• machine learning 机器学习 • neural networks 神经网络 • deep neural network 深度神经网络

Objective

Build the skills to answer exam questions on **Artificial Intelligence** 人工智能 — graphs in AI, neural networks, and the types of machine learning.

You must be able to:

- explain how **graphs** help AI and how an **artificial neural network** works
- compare **supervised**, **unsupervised** and **reinforcement** learning
- explain **deep learning** and **backpropagation**

1 Worked examples

Study these first. Each one shows the method for a question type used later — follow the steps and you can do the Practice and Exam-style questions yourself.

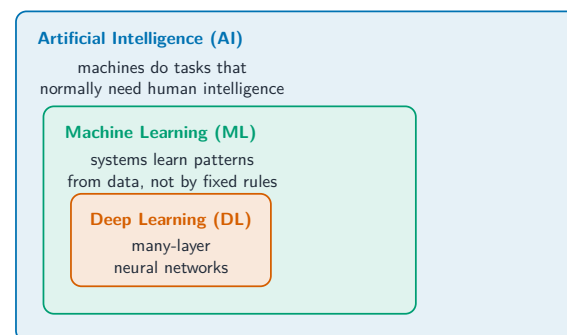
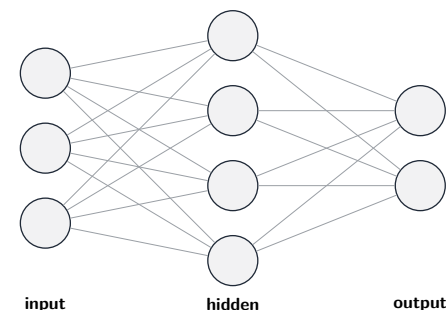
■ AI, ML and graphs

Machine learning (ML) learns patterns **from data** instead of fixed rules; **deep learning (DL)** is ML using deep neural networks. Many AI problems sit on a **graph** — **nodes** (states/places) joined by **edges** (moves, each with a cost). Two algorithms find the **shortest path**:

- **Dijkstra's algorithm** explores outward from the start, always extending the lowest-cost node, until it reaches the goal.
- **A*** does the same but adds a **heuristic** estimate of the distance **still to go**, which steers the search **toward the goal** — so it usually checks **fewer nodes** and is faster.

■ Neural networks

A network has an **input** layer, one or more **hidden** layers, and an **output** layer. Each connection has a **weight**; a neuron sums its weighted inputs (plus a bias), applies an **activation function**, and passes the result on:



How AI, machine learning and deep learning relate

■ Types of machine learning

- **supervised** — data has **labels**; learns input → label (classification, regression).
- **unsupervised** — **no labels**; finds structure (e.g. **clusters**).
- **reinforcement** — an **agent** acts, gets a **reward**, and learns a **policy** that maximises total reward by trial and error.

Training adjusts the weights by **backpropagation**: a forward pass computes the output, a **loss function** measures the error, and the error is propagated **backwards** to update each weight (gradient descent). Deep learning needs **lots of data and compute**.

2 Practice

Now apply the methods above.

2.1 State what **machine learning** is. [1]

2.2 Name the **three** kinds of layer in a neural network. [2]

2.3 In a graph used for **pathfinding**, state what an **edge** represents. [1]

2.4 State what a **weight** is in an artificial neuron. [1]

3 Exam-style questions

3.1 Describe the difference between **supervised** and **unsupervised** learning. [2]

3.2 Explain how **reinforcement learning** works, using the terms **agent**, **reward** and **policy**. [3]

3.3 Explain why **deep learning** needs a large amount of **data** and **computing power**. [2]

3.4 State the role of **backpropagation** in training a neural network. [2]

3.5 State the purpose of **Dijkstra's algorithm** and **A***, and outline **one** difference between them. [3]

3.6 A delivery company is building software to plan its routes and to read handwritten address labels.

(a) **Identify** one Artificial Intelligence algorithm suitable for finding the shortest distance between two depots on a road network, and **state** what the nodes and the edge weights represent. [3]

(b) **Describe** how that algorithm proceeds from the starting node. [3]

(c) The company also considers the **A*** algorithm. **State** the one thing A* uses that the algorithm in (a) does not, and **explain** the benefit. [3]

(d) **Describe** what is meant by **Deep Learning**, and **state** one example of where it is used. [3]

(e) **Explain** why Deep Learning suits the handwriting-reading task better than a set of hand-written rules. [3]

Solutions

Each answer shows the steps, then the **result**.

2.1

- algorithms that **learn patterns from data** (and improve with experience) instead of being programmed with explicit rules

2.2

- **input** layer, **hidden** layer(s), **output** layer

2.3

- a **move/connection** between states (e.g. a road between two places), often with a **cost/weight**

2.4

- a value each input is **multiplied by**, setting how strongly that input affects the neuron's output

3.1

- **supervised** learning trains on **labelled** data (each input has a known correct output)
- **unsupervised** learning uses **unlabelled** data and finds structure/clusters itself

3.2

- an **agent** takes an **action** in an environment, which changes the state and returns a **reward**
- over many trials it learns a **policy** (strategy)
- that **maximises total reward** by trial and error

3.3

- deep networks have **very many weights** to learn
- so they need large datasets to learn good patterns and heavy compute (GPUs) to train in reasonable time

3.4

- it propagates the output **error backwards** through the layers
- to **adjust each weight** so the network's output gets closer to the target (gradient descent)

3.5

- both find the **shortest path** between two nodes in a weighted graph
- **A*** uses a **heuristic** to estimate the remaining distance and head toward the goal, so it usually explores **fewer nodes / is faster**
- **Dijkstra's** has no heuristic and explores outward uniformly

3.6

(a) Dijkstra's algorithm

- the **nodes** are the depots and road junctions
- the **edge weights** are the distances, or the travel times, along each road between them

(b) it gives the start node a distance of zero and every other node infinity

- it then repeatedly takes the **unvisited node with the smallest known distance**, and for each of its neighbours checks whether going via this node is shorter than the distance recorded so far, updating it if so
- the node is then marked visited and never reconsidered; the process ends when the destination is visited

(c) A* also uses a **heuristic** — an estimate of the remaining distance from each node to the goal, such as the straight-line distance

- it therefore explores nodes that head **towards** the destination first
- so it usually examines far fewer nodes than Dijkstra while still finding the shortest route, provided the heuristic never overestimates

(d) Deep Learning uses an **artificial neural network with many hidden layers**

- trained on large amounts of data, where each layer learns features built from the layer before it
- examples: speech recognition, image and face recognition, machine translation, self-driving vehicles

(e) handwriting varies enormously between people, so the rules that distinguish a 7 from a 1 cannot be written out completely

- a network **learns** the distinguishing features from thousands of labelled examples instead of being told them
- and it generalises to handwriting it has never seen, which a fixed rule set cannot do